

Corrigendum for: S. M. N. Mahmud, S. A. Nivison, Z. I. Bell, and R. Kamalapurkar, “Safe model-based reinforcement learning for systems with parametric uncertainties,” *Front. Robot. AI*, vol. 8, no. 733104, pp. 1–13, 2021. DOI: [10.3389/frobt.2021.733104](https://doi.org/10.3389/frobt.2021.733104)

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**Correction:** Equation 12 should be  $\dot{\hat{\theta}} = \beta_1 (X_f - Y_f \hat{\theta})$